

ABSTRACT OF THE DISCLOSURE

An apparatus for grasping odd-shaped objects to relocate the same includes an upright main frame being attachable to a material handling vehicle for maneuvering the main frame between different heights and locations by operation of the material handling vehicle, a support member mounted at a lower end of the main frame and being adapted to engage an edge of an object, an arm member mounted at an upper end of the main frame so as to undergo pivotal movement relative to the main frame, a tine mounting member mounted to the arm member so as to undergo pivotal movement relative to and independently of the arm member, a pair of tines each having a substantially curved configuration and being mounted to and extending outwardly and downwardly from the tine mounting member, and main and auxiliary actuation mechanisms for respectively pivotally moving the arm member relative to the main frame and the tines relative to the arm member through respective first and second arcuate paths toward and away from the support member and an object between the tines and support member such that the tines and support member together may grasp the object for relocating the object upon maneuvering of the apparatus by operation of the material handling vehicle.